

Appendix A

Notation

Scalars, Vectors, and Matrices

Scalars Scalars are denoted by plain (not boldface) characters, such as x, a, i, μ .

Vectors Vectors are denoted by boldface characters, so, for example, $\mathbf{x} = (x_1, x_2, \dots, x_n)$.

Matrices Matrices are denoted by boldface uppercase characters, such as $\mathbf{A} = [a_{ij}]$ where a_{ij} denotes the element in the i^{th} row and j^{th} column of \mathbf{A} . The i^{th} row of a matrix \mathbf{A} is denoted \mathbf{A}^i , and the j^{th} column is denoted \mathbf{A}_j .

Inner products The inner product of two vectors \mathbf{x} and \mathbf{y} is denoted $\mathbf{x}^\top \mathbf{y}$ and is defined by

$$\mathbf{x}^\top \mathbf{y} = \sum_{i=1}^n x_i y_i.$$

The inner product of a matrix \mathbf{A} and a vector \mathbf{x} is denoted $\mathbf{A}^\top \mathbf{x}$ and is defined as the vector

$$\mathbf{A}^\top \mathbf{x} = (\mathbf{A}^1 \mathbf{x}, \mathbf{A}^2 \mathbf{x}, \dots, \mathbf{A}^n \mathbf{x}).$$

The following is a list of variables along with a description of their typical meanings throughout the text.

Roman Variables

\mathbf{A} Incidence matrix for a network model $\mathbf{A} = [a_{ij}]$, where $a_{ij} = 1$ if resource i is used by product j and $a_{ij} = 0$ otherwise; m rows, n columns.

\mathbf{A}^i The i^{th} row of the incidence matrix \mathbf{A} .

A^i The set of products that use resource i .

\mathbf{A}_j The j^{th} column of the incidence matrix \mathbf{A} . Also used to denote the set of resources used by product j .

A_j The set of resources used by product j .

$B_j(y, D)$ The j^{th} "fill event."

b_j Booking limit or nested booking limit.

- $c, c(\mathbf{x})$ Variable cost of production; cost function. Used in economics and overbooking models
- C_i, \mathbf{C} Initial capacity of resource i ; vector of initial capacities. Also used to denote the j^{th} complete set, $C_j = \{1, \dots, j\}$.
- $d_j, \mathbf{d}, d(\mathbf{p}), \mathbf{d}(\mathbf{p})$ Demand (deterministic or mean) for product j ; vector of demands. A demand function depending on price \mathbf{p} ; vector demand function.
- D_j, \mathbf{D} Demand (random variable) for product j ; vector of demand random variables.
- h_{ij}, \mathbf{h} Cost parameters or vector of cost parameters in an overbooking models.
- i Generally indexes resources but also used as a generic index.
- j Generally indexes products but also used as a generic index.
- $J(\mathbf{p}), J(v)$ The marginal revenue as a function of price; the virtual value of a buyer with value v .
- k Capacity cost in economics models; generic integer variable.
- m The number of resources; generic integer variable.
- n The number of products; generic integer variable.
- N Population size or market potential in a pricing or an auction model.
- \mathcal{N} Denotes the set $\{1, 2, \dots, n\}$ (e.g., set of n choice alternatives).
- $p_j(t), \mathbf{p}(t), p_j, \mathbf{p}$ Price of product j at time t or vector of prices at time t ; static price of product j ; vectors of static prices.
- q_j, q_t, \mathbf{q} The probability that a customer shows up (e.g., the probability that class j does not cancel); vectors of probabilities.
- $R(v)$ Expected revenue in an auction for buyer with value v .
- S, \mathbf{S}_k A subset of product classes or alternatives in a choice model; also used to represent a sum of random variables.
- t Used to index time, either in discrete or continuous time.
- T The number of periods in a discrete-time problem or the length of the horizon in a continuous-time problem. Also used to denote a generic set.
- $u_j, \mathbf{u}, \mathbf{u}(t), \mathbf{u}(\mathbf{x})$ Control variables in a dynamic program or other optimization problem, most often an accept or deny decision or a quantity decision. Also, u_j is used to denote the mean of a random-utility U_j in a random-utility model or to denote a utility function in economics models as in $u(\mathbf{x})$ is the utility of \mathbf{x} .
- U_j, \mathbf{U} Random utility (random variable); vector of random utilities.
- v_j, \mathbf{v} Reservation price (private value) of customer j ; vector of reservation price (private values).
- $V_j(\mathbf{x}), V_i(\mathbf{x})$ Optimal value function.
- $V_i^M(\mathbf{x})$ A given approximation M to the optimal value function (e.g., $V_i^{DLP}(\mathbf{x})$ is the approximation of the value function produced by the deterministic linear program (DLP) model).
- x_i, \mathbf{x} Capacity variable; vector of capacities. For example, the remaining capacity of resource i in a dynamic program or the quantity of capacity chosen by firm i . Also used as the decision variable in overbooking models, where it represents the

- overbooking limit (virtual capacity). Vector of such state variables or capacities. Finally, used as capacity- or quantity-choice variable in economic models.
- $\mathbf{y}, \mathbf{y}_j, y$ Allocation variable or protection level for product j ; vector of allocations or protection levels. Used in models for finding partitioned or nested allocations. Also the state variable (number of reservations on hand) in overbooking models.
- z_t Notation used in forecasting. Data value of a forecast observed at time t (realization of random variable Z_t).
- \hat{z}_t Notation used in forecasting. Forecast (point estimate) of time-series value at time t (estimate of unrealized value Z_t).
- Z_t Notation used in forecasting. The t^{th} random variable in a time series Z_1, Z_2, \dots
- $Z(x), Z(y)$ Number of customers who show up (number of survivals) from a given number x, y of reservations on hand. Used in overbooking models.
- $\bar{Z}(x)$ Number of customers who cancel from a given number x of reservations on hand; $\bar{Z}(x) = x - Z(x)$.

Greek Variables

- λ, λ_j An arrival rate in a deterministic demand model and arrival intensity or arrival probability in a probabilistic-demand model.
- Δ The first-difference operator; if $g(x)$ is a function, then $\Delta g(x) = g(x) - g(x - 1)$.
- $\epsilon(p), \epsilon_{ij}(p)$ The elasticity of demand; the cross-price elasticity of demand for product i with respect to the price of product j .
- μ The mean of a random variable.
- $\Omega, \Omega_p, \Omega_d$ A constraint set; the constraint set of prices p and demand rates d .
- $\pi_i, \pi_i(x), \pi$ A bid price value or function—or a dual price from a math program.
- σ The variance of a random variable.
- θ A generic parameter of a distribution or a scaling parameter.
- $\Phi(z)$ The standard normal distribution (i.e., $\Phi(z) = \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-z^2/2} dz$).
- $\phi(z)$ The standard normal density (i.e., $\phi(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$).
- $\psi_X(t)$ The moment-generating function of a random variable X .
- ω An elementary outcome in a probability space (e.g., a random variable is $X(\omega)$).

Miscellaneous Symbols and Notation

- $\mathbb{R}, \mathbb{R}_+, \mathbb{R}^n, \mathbb{R}_+^n$ The set of real numbers ($+\infty, +\infty$); the set of nonnegative real numbers $[0, +\infty)$; the n -dimensional real plane and the n -dimensional positive orthant.
- \mathbb{Z} The set of integers, $\{\dots, -2, -1, 0, 1, 2, \dots\}$.
- $\mathbf{x}^\top, \mathbf{A}^\top$ The transpose of a vector \mathbf{x} or a matrix \mathbf{A} .
- $x^+, (a - b)^+$ The positive part of x equal to $\max\{0, x\}$; the positive part of the quantity $(a - b)$.
- $x^-, (a - b)^-$ The negative part of x equal to $\max\{0, -x\}$; the negative part of the quantity $(a - b)$.

- e_j The j^{th} unit vector; a vector with one in the j^{th} component and zero in all other components.
- \mathbf{x}_{-j} The vector \mathbf{x} without the j^{th} component; that is, the vector $\mathbf{x}_{-j} = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_n)$.
- C^1, C^2 The class of continuously differentiable functions on \mathfrak{R}^n ; the class of all twice-continuously differentiable functions on \mathfrak{R}^n .

Abbreviations

- a.s.** Almost surely.
- c.d.f.** Cumulative distribution function.
- i.i.d.** Independent and identically distributed.
- p.d.f.** Probability-density function.
- p.m.f.** Probability mass function.